

Computer vision cracks the leaf code

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Understanding the extremely variable, complex shape and venation characters of angiosperm leaves is one of the most challenging problems in botany. Machine learning offers opportunities to analyze large numbers of specimens, to discover novel leaf features of angiosperm clades that may have phylogenetic significance, and to use those characters to classify unknowns. Previous computer vision approaches have primarily focused on leaf identification at the species level. It remains an open question whether learning and classification are possible among major evolutionary groups such as families and orders, which usually contain hundreds to thousands of species each and exhibit many times the foliar variation of individual species. Here, we tested whether a computer vision algorithm could use a database of 7,597 leaf images from 2,001 genera to learn features of botanical families and orders, then classify novel images. The images are of cleared leaves, specimens that are chemically bleached, then stained to reveal venation. Machine learning was used to learn a codebook of visual elements representing leaf shape and venation patterns. The resulting automated system learned to classify images into families and orders with a success rate many times greater than chance. Of direct botanical interest, the responses of diagnostic features can be visualized on leaf images as heat maps, which are likely to prompt recognition and evolutionary interpretation of a wealth of novel morphological characters. With assistance from computer vision, leaves are poised to make numerous new contributions to systematic and paleobotanical studies.

leaf architecture | leaf venation | computer vision | sparse coding | paleobotany

Leaves are the most abundant and frequently fossilized plant organs. However, understanding the evolutionary signals of angiosperm leaf architecture (shape and venation) remains a significant, largely unmet challenge in botany and paleobotany (1–3). Leaves show tremendous variation among the hundreds of thousands of angiosperm species, and a single leaf can contain many thousands of vein junctions. Numerous living angiosperm clades supported by DNA data do not have consistently recognized leaf or even reproductive characters (4); the clades' fossil records are often lacking or poorly known (5) but are probably “hiding in plain sight” among the millions of fossil leaves curated at museums. Leaf fossils are most commonly preserved in isolation, lacking standard botanical cues such as arrangement, organization, stipules, trichomes, and color (6). Moreover, improved ability to identify living foliage would advance field botany because most plants flower and fruit infrequently (7, 8).

The only major survey of leaf architectural variation is more than 40 y old (1), long preceding the reorganization of angiosperm phylogeny based on molecular data (9, 10). Traditional leaf architectural methods (11, 12) are extremely labor-intensive, inhibiting detailed analyses of leaf variation across angiosperms; accordingly, recent studies have been limited in taxonomic and character coverage (3, 13, 14). Modern machine learning and computer vision methods offer a transformative opportunity, enabling the quantitative assessment of leaf features at a scale never before remotely possible. Many significant computer vision contributions have focused on leaf identification by analyzing leaf-shape variation among

species (15–19), and there is community interest in approaching this problem through crowd-sourcing of images and machine-identification contests (see www.imageclef.org). Nevertheless, very few studies have made use of leaf venation (20, 21), and none has attempted automated learning and classification above the species level that may reveal characters with evolutionary significance. There is a developing literature on extraction and quantitative analyses of whole-leaf venation networks (22–25). However, those techniques mostly have not addressed identification problems, and they are methodologically limited to nearly undamaged leaves, which are rare in nature and especially in the fossil record.

Despite the numerous difficulties involved in analyzing leaf architecture, experienced botanists regularly identify leaves to species and higher taxonomic categories quickly and correctly, often without the use of verbally defined characters (“leaf gestalt”). Here, we attempt to automate leaf gestalt, using computer vision and machine learning on a database of several thousand cleared-leaf images to test whether an algorithm can generalize across diverse genera and species to learn, recognize, and reveal features of major angiosperm clades. This challenge is wholly different from that of identifying species, as typically practiced in the computer vision field (see above discussion), because the leaf variation within a species is nearly insignificant compared with that among species within a family or order, as seen in example leaf pairs from various families (Fig. 1). Nevertheless, generations of botanists and paleobotanists have emphasized the recognizability of leaf traits at the family and higher

Significance

The botanical value of angiosperm leaf shape and venation (“leaf architecture”) is well known, but the astounding complexity and variation of leaves have thwarted efforts to access this underused resource. This challenge is central for paleobotany because most angiosperm fossils are isolated, unidentified leaves. We here demonstrate that a computer vision algorithm trained on several thousand images of diverse cleared leaves successfully learns leaf-architectural features, then categorizes novel specimens into natural botanical groups above the species level. The system also produces heat maps to display the locations of numerous novel, informative leaf characters in a visually intuitive way. With assistance from computer vision, the systematic and paleobotanical value of leaves is ready to increase significantly.

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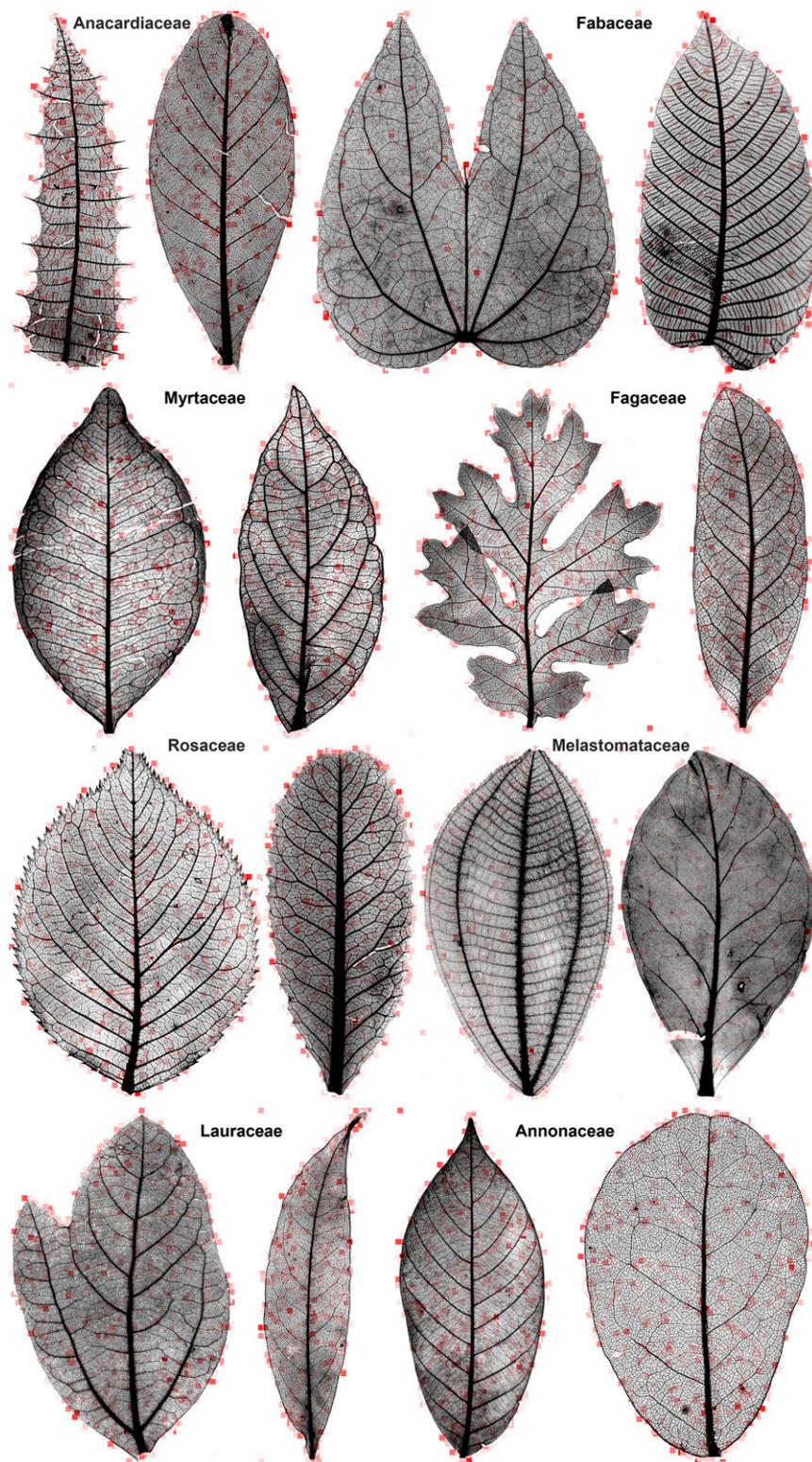


Fig. 1. Representative heat maps on selected pairs of leaves from analyzed families, showing typical variation among species within families. Red intensity indicates the diagnostic importance of an individual codebook element at a leaf location for classifying the leaf into the correct family in the scenario of Fig. 3A. The locations and intensities correspond to the maximum classifier weights associated with the individual codebook elements (*Materials and Methods*). For readability, only coefficients associated with the 1×1 scale of the spatial pyramid grid are shown; most elements have zero activation on a given leaf. Background areas show some responses to minute stray objects. All images are shown with equal longest dimensions (here, height), as processed by the machine-vision system; see [Dataset S1](#) for scaling data. Specimens from Wolfe National Cleared Leaf Collection as follows. First row, left to right: Anacardiaceae, *Comocladia acuminata*, Wolfe (catalog no. 8197) and *Campnosperma minus* (catalog no. 8193); Fabaceae, *Bauhinia glabra* (catalog no. 30215) and *Dussia micranthera* (catalog no. 9838). Second row: Myrtaceae, *Myrcia multiflora* (catalog no. 3543) and *Campomanesia guaviroba* (catalog no. 3514); Fagaceae, *Bauhinia lobata* (catalog no. 1366) and *Chrysolepis sempervirens* (catalog no. 7103). Third row: Rosaceae, *Prunus subhirtella* (catalog no. 8794) and *Heteromeles arbutifolia* (catalog no. 11992); Melastomataceae, *Conostegia caelestis* (catalog no. 7575) and *Mecycylon normandii* (catalog no. 14338). Fourth row: Lauraceae, *Sassafras albidum* (catalog no. 771) and *Aiouea saligna* (catalog no. 2423); Annonaceae, *Neostenanthera hamata* (catalog no. 4481) and *Monanthotaxis fornicata* (catalog no. 2866). Extended heat-map outputs are hosted on Figshare, dx.doi.org/10.6084/m9.figshare.1521157.

levels (1, 7, 26). We test this fundamental supposition by asking whether a machine vision algorithm can perform a comparable task, learning from examples of large evolutionary categories (families or orders) to correctly discriminate other members of those lineages. We then visualize the machine outputs to display which regions of individual leaves are botanically informative for correct assignment above the species level.

To train the system (see *Materials and Methods* for details), we vetted and manually prepared 7,597 images of vouchered, cleared angiosperm leaves from 2,001 phylogenetically diverse genera and ca. 6,949 species from around the world, and we updated nomenclature to the Angiosperm Phylogeny Group (APG) III system (10). Cleared leaves (Fig. 1) are mounted specimens whose laminar tissues have been chemically altered and then

stained to allow close study of venation patterns in addition to the leaf outlines. Importantly, we did not, except in severe cases (*Materials and Methods*), exclude leaves with common imperfections such as bubbles or crystallization in the mounting medium, leaf damage (insect, fungal, mechanical), or imaging defects (poor focus, background artifacts). Four sets of images were processed for the analyses: those from the (i) 19 families and (ii) 14 orders with minimum sample sizes of 100 images each and those from the (iii) 29 families and (iv) 19 orders with minimum sample sizes of 50 images each. In all analyses, random halves of the image sets were used to train the system and the other half to test, and this procedure was repeated 10 times. Accuracy measures correspond to averages and SDs across these 10 repetitions.

The computer vision algorithm (see *Materials and Methods* for details; Fig. S1) used a sparse coding approach, which learns a codebook (Fig. 2) from training images and uses it to represent a leaf image as a linear combination of a small number of elements (27). Similar methods have been applied to a variety of problems (28–30). Of interest here regarding “leaf gestalt,” seminal work in vision science (27) showed that training a sparse coding model on images of natural scenes resulted in receptive fields that resemble those of the mammalian visual cortex. Our approach used Scale Invariant Feature Transform (SIFT) visual descriptors (31) extracted from individual locations on the training leaf images to learn a codebook (Fig. 2) and then to model each location as a linear combination of the codebook elements. Support Vector Machine (SVM) (32), a machine-learning classifier, was trained on the pooled maximum coefficients for each codebook element and the associated taxonomic labels (families or orders). Training resulted in a classification function that was applied to predict familial and ordinal identifications of novel images. Heat maps of visualized diagnostic responses were generated directly on individual leaf images (Fig. 1).

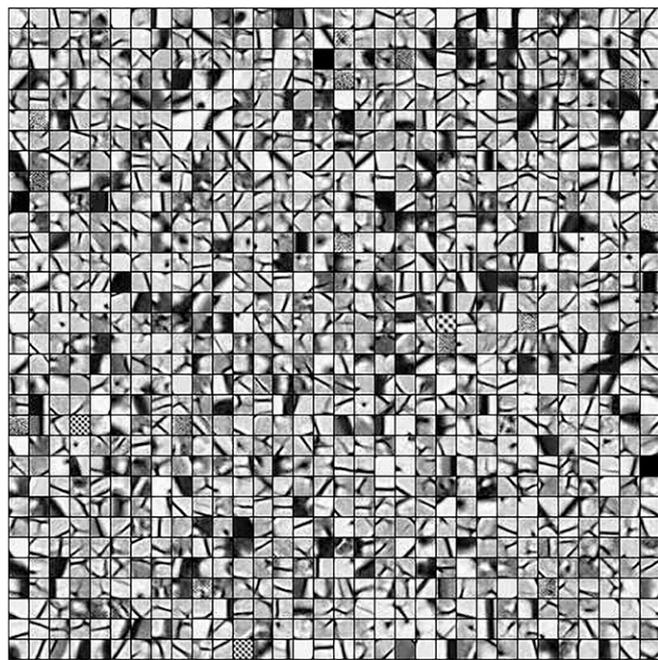


Fig. 2. Learned visual codebook ($n=1,024$ coding elements) obtained from one random split of the image library. Ten splits were done to compute the reported accuracies (Table 1). A few codebook elements are moiré dots from background areas of scanned book pages (see *Materials and Methods*). Precisely visualizing the codebook is an unsolved problem, and we used a computational approximation (38) to produce this figure.

To our knowledge, no prior approach has adopted this powerful combination of tools for leaf identification, used cleared leaves or analyzed leaf venation for thousands of species, attempted to learn and discriminate traits of evolutionary lineages above the species level, or directly visualized informative new characters.

Results

Classification accuracy was very high (Fig. 3 and Fig. S2), especially considering the well-known challenges of identifying leaves to higher taxa visually and the deliberate inclusion of many imperfect specimens and low-quality images. Accuracy for the 19 families with ≥ 100 images was $72.14 \pm 0.75\%$, ca. 13 times better than random chance ($5.61 \pm 0.54\%$; accuracy is defined as the grand mean and SD of the 10 trial averages of the diagonal values of the confusion matrices, as in Fig. 3). Thus, the algorithm successfully generalized across a few thousand highly variable genera and species to recognize major evolutionary groups of plants (see also *Materials and Methods, Success in Generalization of Learning across Taxonomic Categories and Collections*). Significantly, the system scored high accuracies ($>70\%$) for several families that are not usually considered recognizable from isolated blades, including Combretaceae, Phyllanthaceae, and Rubiaceae. Of great biological interest, our heat maps directly illustrate leaf features that are diagnostic for classification (Fig. 1; extended heat-map outputs are hosted on Figshare, [dx.doi.org/10.6084/m9.figshare.1521157](https://doi.org/10.6084/m9.figshare.1521157)).

Accuracy at the ordinal level was also many times greater than chance. This result partly reflects the recognition of the constituent families rather than generalization across families to recognize orders; however, even after testing for this effect, there was still a significant signal for generalization (*Materials and Methods*). On first principles, generalization across genera to recognize families should be more successful, as seen here, than generalization across families to distinguish orders. The genera within a family are usually much more closely related to each other, and thus likely to be phenotypically similar, than are the families within an order. Hypothetically, an increased number of well-sampled families in targeted orders would allow improved recognition of orders and generalization across families (see also Fig. S3). Artifacts specific to particular image sets contributed noise but were largely overcome (*Materials and Methods*), boding well for applying the system to a range of new and challenging datasets.

For a benchmark comparison, we classified the images from the 19 families in Fig. 3A via holistic analysis of leaf shape alone. We compared the well-known shape-context algorithm (15) (*Materials and Methods*) with our sparse coding algorithm on extracted leaf outlines. For family classification at the 100-image minimum, shape context performed above random chance ($12.44 \pm 0.74\%$ vs. $5.61 \pm 0.54\%$ chance result) but below sparse coding of the same outlines ($27.94 \pm 0.85\%$), and both scored far below sparse coding of images with venation (ca. 72%; Fig. 3A). These results help to demonstrate the diagnostic significance of both leaf venation and shape. The importance of leaf venation is long established (26). However, the results from leaf outlines refute the widely held view, seen in many of the hundreds of papers cited in the extended bibliography of ref. 33, that leaf shape is principally selected by climate and that phylogeny plays a negligible role.

Discussion

All of our results validate the hypotheses that higher plant taxa contain numerous diagnostic leaf characters and that computers can acquire, generalize, and use this knowledge. In addition to the potential for computer-assisted recognition of living and fossil leaves, our algorithm represents an appealing, novel approach to leaf architecture. Conventional leaf architecture (12) currently employs ca. 50 characters to describe a range of characters that are usually visible over large areas of a specimen,

for the second suggests that the system exhibits robust generalization across genera to recognize families, and is not, for example, dependent on well-sampled genera such as *Acer* (maples, Sapindaceae) and *Quercus* (oaks, Fagaceae). The higher possibility of identification errors for genera than for families on the original samples biases against this positive result, which confirms conventional wisdom regarding the general identifiability of families as well as the potential for machine vision to recognize finer taxonomic levels.

We also explored the extent to which the machine-vision system may be exploiting possible biases associated with individual collections, such as the moiré printing pattern in the Klucking images. We conducted an experiment in which we selected all orders that had at least 50 images each in both the Klucking and the Wolfe collections, namely Laurales, Magnoliales, Malpighiales, Malvales, and Myrtales. We trained and tested the system in three scenarios, following the same methods that we used in the main experiments. First, we trained on the Klucking and tested on the Wolfe image collection (accuracy of order recognition: $37.44 \pm 0.66\%$; chance level: $19.40 \pm 3.53\%$). Second, we trained on the Wolfe and tested on the Klucking collection (accuracy of order recognition: $41.12 \pm 0.94\%$; chance level: $20.04 \pm 5.00\%$). Third, we combined the two sources and randomly sampled half the images from each order for training and half for testing (accuracy of order recognition: $64.68 \pm 2.65\%$; chance level: $18.96 \pm 3.78\%$). The higher accuracy in scenario 3 suggests that biases exist (e.g., image background) that can be picked up by the system. However, the significant generalization of the system in scenarios 1 and 2, especially when taking into account the overall much lower image quality of the Klucking collection, suggests that these biases only account for a small fraction of the overall system accuracy.

Benchmark Using Shape Context. The shape-context algorithm has been successfully used for species-level leaf classification (15). We tested both the shape-context and sparse-coding algorithms on leaf outlines extracted from the same image subset used for the 19 family, 100-image-minimum scenario shown in Fig. 3A. Leaves were segmented automatically by combining the Berkeley contours detection system (37) with second-order Gaussian derivative filters, and the corresponding closed boundary was then filled to obtain foreground masks. Shape-context features were then extracted from the leaf silhouette, following the approach of Ling and Jacobs (15). Leaf contours were sampled uniformly at 128 landmark points, and shape-context descriptors were extracted at every sampled point, using source code available online (www.dabi.temple.edu/~hbling/code_data.htm). This procedure led to a 96×128 dimensional visual representation (the shape context) for each leaf image. Matching between two leaves' shape contexts was obtained through dynamic programming, where matching cost is used to measure similarity. The pairwise similarities were then used to derive a Kernel matrix that was fed to an SVM, which was trained and tested using the same pipeline as for the sparse model described in *Materials and Methods, Computer Vision Algorithm*.

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Supporting Information

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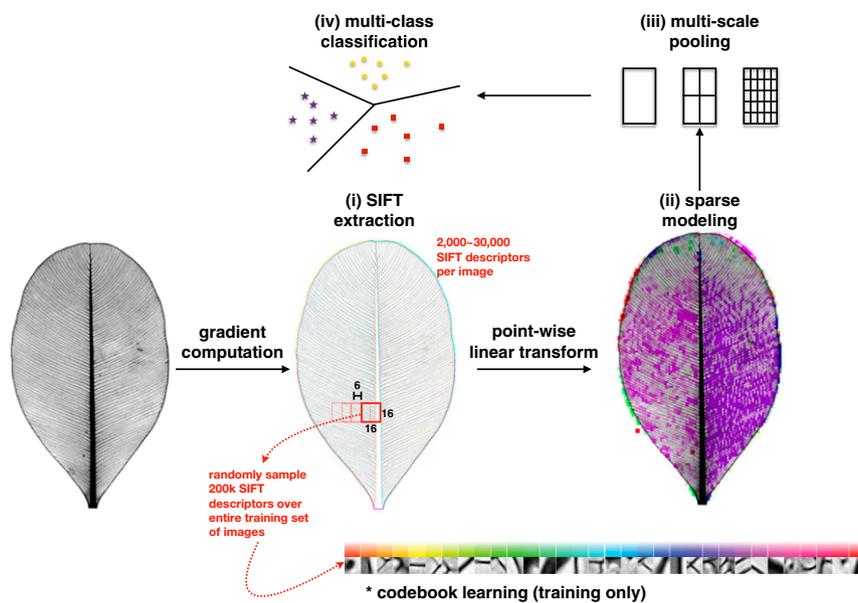


Fig. S1. Computer vision system summary.

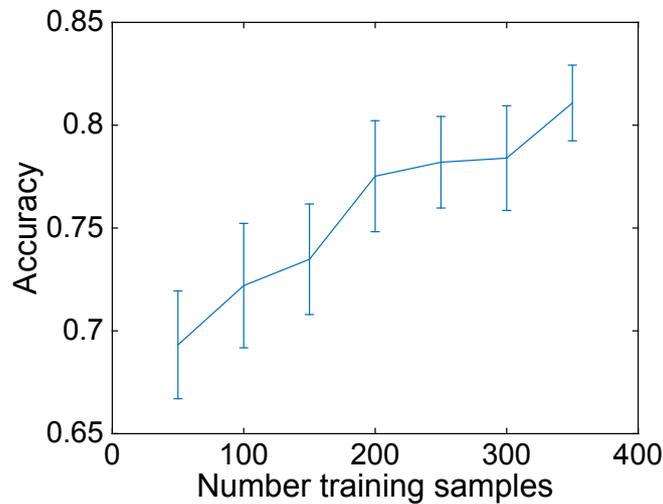


Fig. S3. System accuracy as a function of the number of training samples available per category, for five orders with at least 400 images each (Fabales, Gentianales, Malpighiales, Myrtales, and Sapindales).

Dataset S1. Complete list of imaged specimens analyzed and confusion matrices

[Dataset S1](#)

The dataset contains a complete list of imaged specimens analyzed (first tab) and confusion matrices for the four main experiments shown in Fig. 3 and Fig. S2 on remaining tabs. On the first tab, specimen numbers listed for the Wolfe collection refer to his catalog numbers for the individual mounted slides. The full catalog, including Wolfe's annotations of source herbarium sheets, is maintained with the slides at the Smithsonian National Museum of Natural History, Division of Paleobotany. The catalog numbers can be used to locate the unprocessed images online at clearedleavesdb.org. Specimen numbers for the Klucking collection refer to the volume, plate, and figure of the image that we scanned from ref. 36, which lists all herbarium sources. Specimen numbers for the Axelrod collection represent the mounted slides housed at the University of California Museum of Paleontology, which maintains all linked herbarium records and online images, ucmp.berkeley.edu/science/clearedleaf.php. "Mag.X" refers to the amount of image magnification. The confusion matrices are based on a single randomized test trial (of 10 total) on half of the image set, following training on the other half. Total accuracies over all 10 trials are shown in Table 1 and the captions to Fig. 3 and Fig. S2, showing negligible variance across trials.

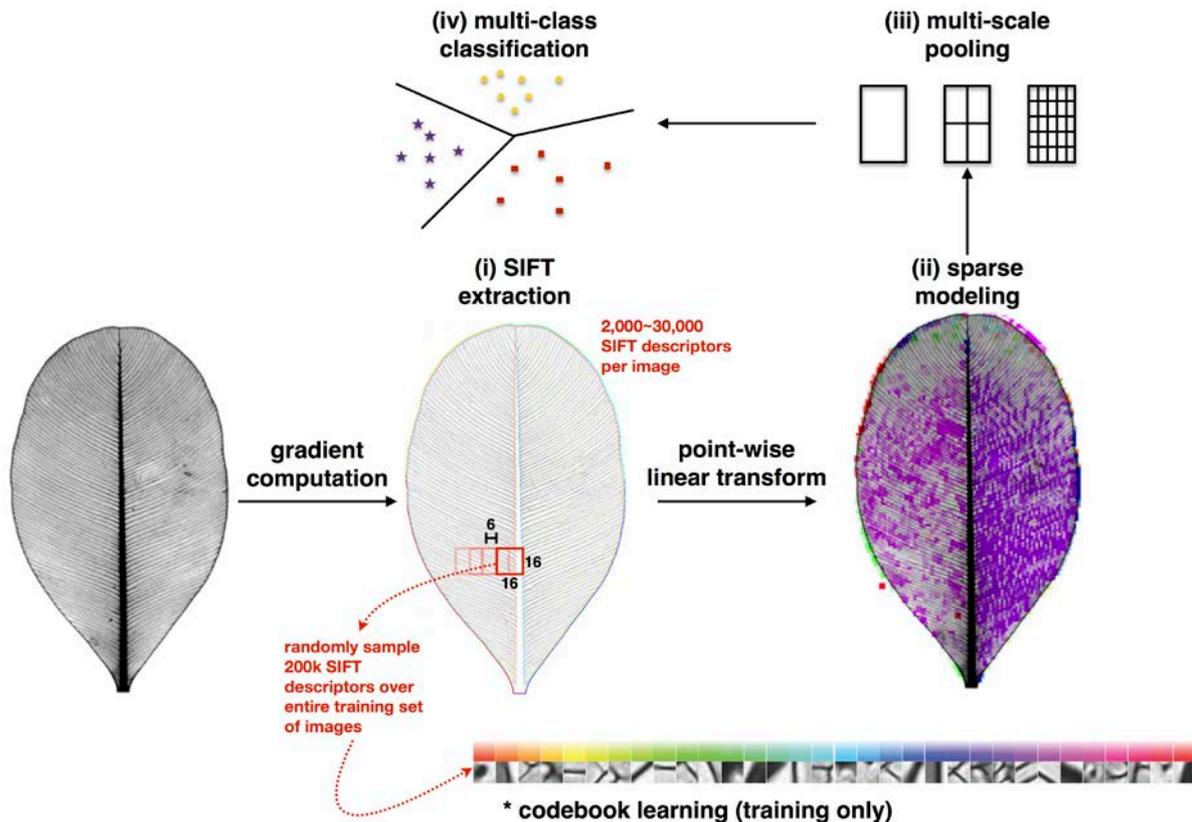
Dataset S2. Archive of computer code developed

[Dataset S2](#)

Dataset S2. Archive of computer code developed.

This supplementary material contains the MATLAB code used to produce the results reported in the paper as well as corresponding documentation.

1. System Overview



The computer vision based leaf recognition system consists of four stages including *SIFT extraction*, *sparse modeling*, *multi-scale pooling* and *multi-class classification*.

SIFT extraction stage

- Each leaf image is first resized such that its maximum length or width dimension is 1024 pixels, while maintaining aspect ratio.
- Image patches with size of 16x16 in pixel are densely sampled from each resized leaf image with partial overlap.
- A 128-dimensional SIFT descriptor is extracted from each image patch.

Sparse modeling

- Given a training set of 128-dimensional SIFT descriptors, a sparse coding dictionary with 1024 elements is first learned.
- For any 128-dimensional SIFT descriptor extracted from an image patch of a leaf image, a 1024-dimensional sparse coefficient vector is computed.

Multi-scale pooling

- From each spatial grid, a 1024-dimensional feature vector can be obtained by max pooling sparse coefficient vectors of image patches inside this grid.

- (b) A total of 21 feature vectors are concatenated into a 21504-dimensional feature vector from each leaf image.

Multi-class classification

- (a) Given a training set of 21504-dimensional feature vectors computed from leaf images coming from all classes, a multi-class Support Vector Machine (SVMs) model can be learned.
- (b) For any query leaf image, the 21504-dimensional feature vector computed from it is fed to the learned SVM model, which then outputs its class label.

2. Installation

The code was written in MATLAB and successfully tested using MATLAB R2014a on Windows, Linux and Mac operating systems.

Before running the code contained in this folder, please first download two public toolboxes from the Internet:

- 1) Download the LIBSVM toolbox at <http://www.csie.ntu.edu.tw/~cjlin/libsvm/>, compile it and set up its path in MATLAB.
- 2) Download the SPAMS toolbox at <http://spams-devel.gforge.inria.fr> and compile it and set up its path in MATLAB.

You can download the pre-computed SIFT descriptors of all leaf images from <http://serre-lab.clps.brown.edu/resources/LeafSIFT.zip> and unzip it inside this folder.

3. Run the code

To retrain the models and reproduce the recognition results reported in Table 1 of the manuscript, please first launch MATLAB. Create five individual files with the code included in this pdf and run the command “demo_main.m”.

4. Contact us

If you encounter any problem or if you have questions about the code, please contact us at s.zhang@hit.edu.cn, thomas_serre@brown.edu, or pwilf@psu.edu. We are very interested in hearing how the system and data are used by others, so please let us know if you find this resource useful.

demo_main.m

```
% This code is used to reproduce the recognition results reported in %  
Table 1 of the manuscript. Note that before running this code, please %  
make sure you have downloaded the SIFT descriptors and put them into the  
% folder 'LeafSIFT'  
  
rand('state', 0);  
randn('state', 0);  
  
%% Parameter setting  
task = 'family'; % or 'order'  
threshold = 100; % or 50  
maximalSide = 1024; % the maximum dimension (length or width) in pixels  
split = 0.5; % the proportion of total leaf images used for training  
num_bases = 1024; % the number of elements of the learned sparse coding dictionary  
lc = 100; % SVM parameter  
  
num_patches = 200000; % the number of samples for sparse coding dictionary learning  
param.K = num_bases;  
param.lambda = 0.15; % regularization parameter for sparse coding  
param.numThreads = 4;  
param.batchsize = 400;  
param.iter = 1000;  
  
pyramid = [1, 2, 4]; % spatial pyramid parameters  
nRounds = 10; % the number of running  
bShow = 0;  
  
structure_dir = 'data_structure'; % the directory of the data structure file  
sift_dir = 'LeafSIFT'; % the directory of the SIFT descriptors  
feature_dir = 'features'; % the directory of the features  
dictionary_dir = 'dictionary'; % the directory of the dictionary  
result_dir = 'results'; % the directory of the results  
  
%% load the structure file for the specific recognition task  
data_structure_file = sprintf('%s/%s_%d.mat', structure_dir, task, threshold);  
load(data_structure_file);  
if strcmp(task, 'family')  
    data_structure.class_names = family_names;
```

```

elseif strcmp(task, 'order')
    data_structure.class_names = order_names;
end
data_structure.image_names = image_names;
data_structure.labels = labels;

dim_features = sum(num_bases*pyramid.^2); % the dimension of the final feature vectors fed to SVM
num_images = length(data_structure.image_names);

clabel = unique(data_structure.labels);
nclass = length(clabel);

accuracy = zeros(nRounds, 1);
for r=1: nRounds

    feature_folder = sprintf('%s/Expl_Task_%s_threshold_%d_Resize_%d_split_%4.2f_numBases_%d_Round_%d', ...
        feature_dir, task, threshold, maximalSide, split, num_bases, r);
    if ~exist(feature_folder, 'dir')
        mkdir(feature_folder);
    end

    dictionary_folder =
sprintf('%s/Expl_Task_%s_threshold_%d_Resize_%d_split_%4.2f_numBases_%d_Round_%d', ...
        dictionary_dir, task, threshold, maximalSide, split, num_bases, r);
    if ~exist(dictionary_folder, 'dir')
        mkdir(dictionary_folder);
    end

    % choose training samples and test samples for this round
    samples_file = sprintf('%s/samples_idx.mat', dictionary_folder);
    if ~exist(samples_file, 'file')
        tr_idx = [];
        ts_idx = [];
        for i = 1:nclass,
            idx_label = find(data_structure.labels == clabel(i));
            num = length(idx_label);
            if split < 1
                tr_num = round(num*split);
            else
                tr_num = split;
            end
        end
    end
end

```

```

        end
        idx_rand = randperm(num);

        tr_idx = [tr_idx idx_label(idx_rand(1:tr_num))];
        ts_idx = [ts_idx idx_label(idx_rand(tr_num+1:end))];
    end
    save(samples_file, 'tr_idx', 'ts_idx');
else
    load(samples_file);
end

% learning sparse coding dictionary
dict_file = [dictionary_folder '/dict.mat'];
if ~exist(dict_file, 'file')
    [patches, xs, ys] = Collect_SIFT_descriptors(sift_dir, data_structure, tr_idx, num_patches);
    B = mexTrainDL(patches,param);
    save(dict_file, 'B');
else
    load(dict_file);
end

% Compute sparse coding features
sc_fea_all = zeros(dim_features, num_images);
sc_label_all = data_structure.labels;
for i=1: num_images

    [~, fname] = fileparts(data_structure.image_names{i});
    f_sift_path = fullfile(rt_sift_dir, [fname, '_sift.mat']);
    f_sc_fea_path = fullfile(feature_folder, [fname, '.mat']);
    if ~exist(f_sc_fea_path, 'file')
        fprintf('Compute Sparse coding features for %d/%d image\n', i, num_images);
        load(f_sift_path);
        fea = Compute_Features(feaSet, B, pyramid, param);
        save(f_sc_fea_path, 'fea');
    else
        fprintf('Load Sparse coding features for %d/%d image\n', i, num_images);
        load(f_sc_fea_path);
    end
    sc_fea_all(:, i) = fea;
end
end

```

```

% Perform classification
tr_fea = sc_fea_all(:, tr_idx)';
tr_label = sc_label_all(tr_idx)';
ts_fea = sc_fea_all(:, ts_idx)';
ts_label = sc_label_all(ts_idx)';

kparam = 1;
Ktr = Compute_RBF_kernel(tr_fea, tr_fea, kparam);
Kte = Compute_RBF_kernel(ts_fea, tr_fea, kparam);
Ktr = double([(1:size(Ktr,1))' Ktr]);
Kte = double([(1:size(Kte,1))' Kte]);

option = ['-t 4 -c ' num2str(lc)];
[C, decmatrix, traintime, testtime] = libsvmova(tr_label, Ktr, ts_label, Kte, lc);

leaf_frame_acc = mean(C == ts_label);

confusion_matrix = genConfus(ts_label, C, data_structure.class_names, bShow);
accuracy(r) = mean(diag(confusion_matrix));

end

% save the results
save(result_file, 'accuracy');

```

Collect_SIFT_descriptors.m

```

function [descriptors, xs, ys] = Collect_SIFT_descriptors(sift_folder, data_structure, tr_idx,
num_descriptors)
% Functionality:
%   Collect a number of SIFT descriptors from the training leaf images
%   for learning the sparse coding dictionary
% Input:
%   sift_folder    --- the folder where the SIFT descriptors of all leaf
%                   images were saved
%   data_structure --- the structure variable with fields specifying the
%                   names of leaf images and the corresponding labels

```

```

%      tr_idx      --- the indices of training leaf images
%      num_descriptors --- the number of SIFT descriptors to be collected
%                               for dictionary learning
% Output:
%      descriptors  --- a matrix with column vectors being the SIFT
%                               descriptors randomly extracted from training leaf images
%      xs          --- the x coordinates of patches' centers from
%                               whcih the SIFT descriptors were extracted
%      ys          --- the x coordinates of patches' centers from
%                               which the SIFT descriptors were extracted
num_training_images = length(tr_idx);
num_per_img = round(num_descriptors/num_training_images);
num_descriptors = num_per_img*num_training_images;

descriptors = zeros(128, num_descriptors);
xs = zeros(1, num_descriptors);
ys = zeros(1, num_descriptors);
cnt = 0;
for i=1: num_training_images
    fprintf('Extracting training samples for dictionary learning from %d/%d image\n', i,
num_training_images);
    ind = tr_idx(i);
    [~, fname] = fileparts(data_structure.image_names{ind});
    f_sift_path = fullfile(sift_folder, [fname, '_sift.mat']);
    load(f_sift_path);
    num_fea = size(feaSet.feaArr, 2);
    rndidx = randperm(num_fea);
    num_per_img_actural = min(num_fea, num_per_img);
    descriptors(:, cnt+1:cnt+num_per_img_actural) = feaSet.feaArr(:, rndidx(1:num_per_img_actural));
    xs(:, cnt+1:cnt+num_per_img_actural) = feaSet.x(rndidx(1:num_per_img_actural));
    ys(:, cnt+1:cnt+num_per_img_actural) = feaSet.y(rndidx(1:num_per_img_actural));
    cnt = cnt+num_per_img_actural;
end
descriptors = descriptors(:, 1:cnt);
xs = xs(:, 1:cnt);
ys = ys(:, 1:cnt);

```

Compute_Features.m

```

function features = Compute_Features(feaSet, B, pyramid, param)
% Functionality:

```

```

%       Given the SIFT descriptors extracted from a leaf image and the
%       sparse coding dictionary, this function returns the computed
%       features from the leaf image by max pooling the sparse coding
%       responses over the dictionary
% Input:
%       feaSet      --- SIFT descriptors extracted from a leaf image
%       B           --- Sparse coding dictionary
%       pyramid     --- pyramid scale [0, 1, 2]
%       param       --- Sparse coding parameters
% Output:
%       features    --- the computed features from the input leaf image

dSize = size(B, 2);
img_width = feaSet.width;
img_height = feaSet.height;

sc_codes = mexLasso(double(feaSet.feaArr), B, param);

sc_codes = abs(sc_codes);

% spatial levels
pLevels = length(pyramid);
% spatial bins on each level
pBins = pyramid.^2;
% total spatial bins
tBins = sum(pBins);

features = zeros(dSize, tBins);
features_ind = zeros(dSize, tBins);
beta_sum = zeros(dSize, tBins);
bId = 0;

for iter1 = 1:pLevels,

    nBins = pBins(iter1);

    wUnit = img_width / pyramid(iter1);
    hUnit = img_height / pyramid(iter1);

```

```

% find to which spatial bin each local descriptor belongs
xBin = ceil(feaSet.x / wUnit);
yBin = ceil(feaSet.y / hUnit);
idxBin = (yBin - 1)*pyramid(iter1) + xBin;

for iter2 = 1:nBins,
    bId = bId + 1;
    sidxBin = find(idxBin == iter2);
    if isempty(sidxBin),
        continue;
    end
    [features(:, bId), max_ind] = max(sc_codes(:, sidxBin), [], 2);
    features_ind(:, bId) = sidxBin(max_ind);
    beta_sum(:, bId) = sum(sc_codes(:, sidxBin), 2);
end
end

if bId ~= tBins,
    error('Index number error!');
end

features = features(:);
features = features./sqrt(sum(features.^2));

```

Compute_RBF_kernel.m

```

function K = Compute_RBF_kernel(feaset_1, feaset_2, kparam)
% Functionality:
%     Compute the RBF kernel matrix between two sets of features
% Input:
%     feaset_1    --- feature matrix, each row denotes one sample
%     feaset_2    --- feature matrix, each row denotes one sample
%
% Output:
%     K           --- kernel matrix

if (size(feaset_1,2) ~= size(feaset_2,2))
    error('sample1 and sample2 differ in dimensionality!!!');
end

```

```

[L1, dim] = size(feaset_1);
[L2, dim] = size(feaset_2);

% If single parameter, expand it.
if length(kparam) < dim
    a = sum(feaset_1.*feaset_1,2);
    b = sum(feaset_2.*feaset_2,2);
    dist2 = bsxfun(@plus, a, b' ) - 2*feaset_1*feaset_2';
    K = exp(-kparam*dist2);
else
    kparam = kparam(:);
    a = sum(feaset_1.*feaset_1.*repmat(kparam',L1,1),2);
    b = sum(feaset_2.*feaset_2.*repmat(kparam',L2,1),2);
    dist2 = bsxfun(@plus,a,b') - 2*(feaset_1.*repmat(kparam',L1,1))*feaset_2';
    K = exp(-dist2);
end

end

```

genConfus.m

```

function C= genConfus(truth,pred,classes,bDisplay)
% Functionality:
%   Given the ground truth labels of the test samples and the predicted
%   labels by the classifier, this function return the confusion matrix
% Input:
%   truth      --- The ground truth labels of the test samples
%   pred       --- the predicted labels of the test samples
%   classes   --- the names of the multiple classes for classification
%   bDisplay  --- whether display the confusion matrix
% Output:
%   C         --- the confusion matrix

Csize = length(classes);
C = zeros(Csize,Csize);
actionCount = zeros(Csize,1);

for action = 1:Csize
    Tind = find(truth == action);

```

```

Plabel = pred(Tind);
actionCount(action) = length(Tind);
Punique = unique(Plabel);

for i = 1:length(Punique)
    C(action,Punique(i)) = length(find(Plabel == Punique(i))) / length(Tind);
end
end

d = diag(C); dd = d; dd(find(actionCount == 0 )) = [];
diagAcc = mean(dd);

if bDisplay
    displayConfus(C,actionCount,d,diagAcc,truth,pred,classes);
end

function displayConfus(C,actionCount,d,classes)

    action_truth = cell(1,length(classes));
    action_pred = cell(1,length(classes));
    for i = 1:length(classes)
        action_truth{i} = [classes{i} ' ' num2str(actionCount(i))];
        action_pred{i} = sprintf('%d',round(d(i)*100));
    end

    figure,
    imagesc(C),colorbar, xlabel('prediction'), ylabel('human');
    set(gca,'XTick',[1:length(unique(classes))],'XTickLabel',action_pred,'YTick',...
        [1:length(unique(classes))],'YTickLabel',action_truth)

```